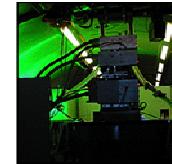
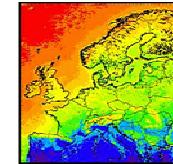
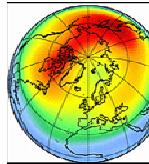


A novel displacement-based measure to assess the quality of mesoscale EPS forecasts

Christian Keil and George C.Craig

Institut für Physik der Atmosphäre
DLR Oberpfaffenhofen, Germany

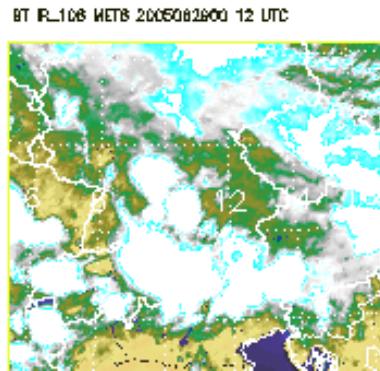


Motivation

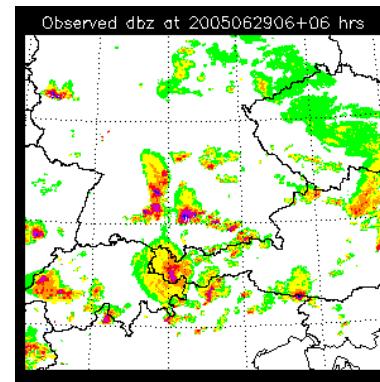
Exploitation of spatio-temporal information contained in remote sensing imagery

Observation

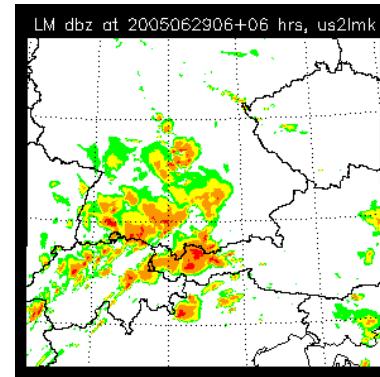
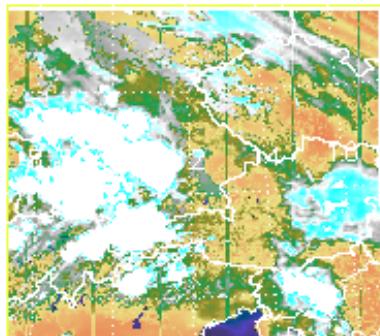
Meteosat 8



Radar



LMK Forecast
using forward operators

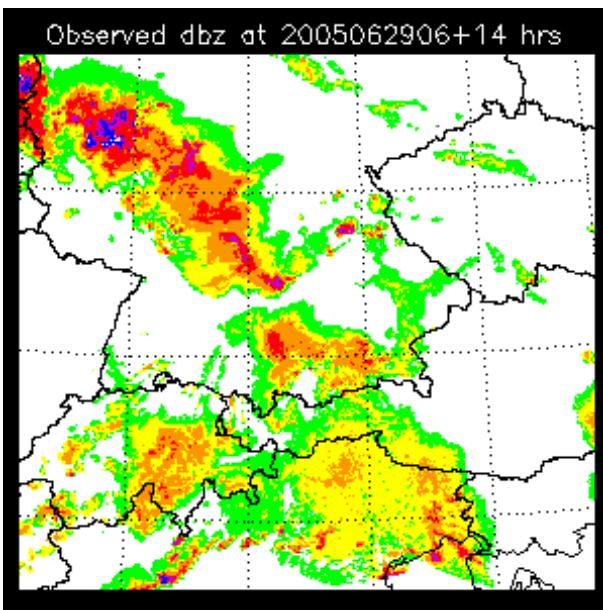


Pyramidal Matching Algorithm (Mannstein et al., 2002)

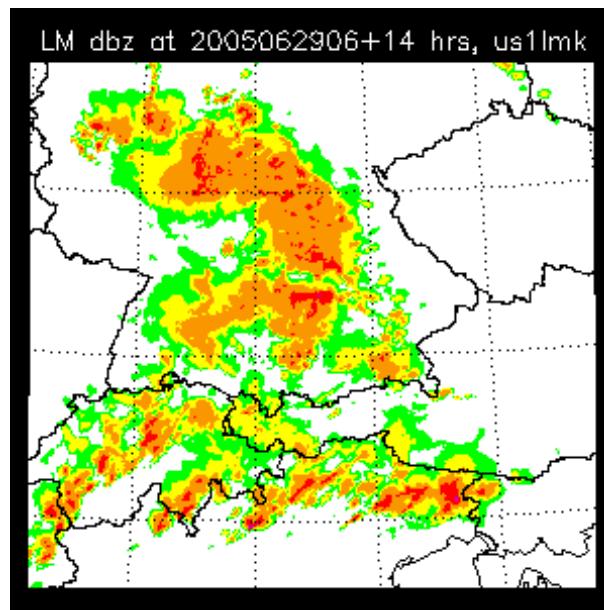
1. **Project** observed and simulated images to same grid
2. **Coarse-grain** both images by averaging of 2^F pixels onto one pixel element
3. **Compute a displacement vector field** that minimizes the squared difference within the range of +/- 2 pixel elements
4. **Repeat** step 2 at successively **finer scales**
5. Displacement vector for every pixel results from the **sum** over all scales

Pyramidal Matching: Example with real data

1. Project observed and simulated images to same grid



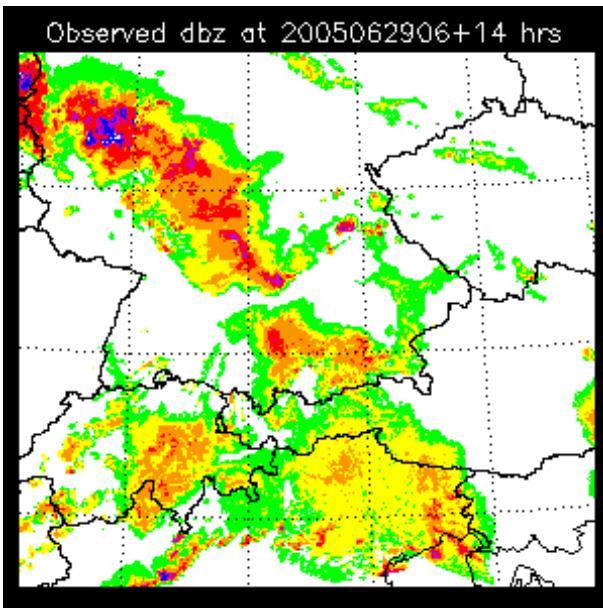
Observation



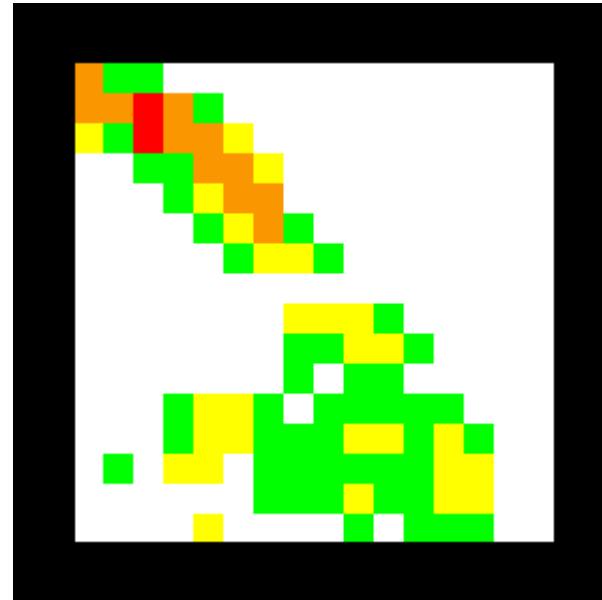
Forecast

Pyramidal Matching: Example with real data

2. Coarse-grain both images by pixel averaging



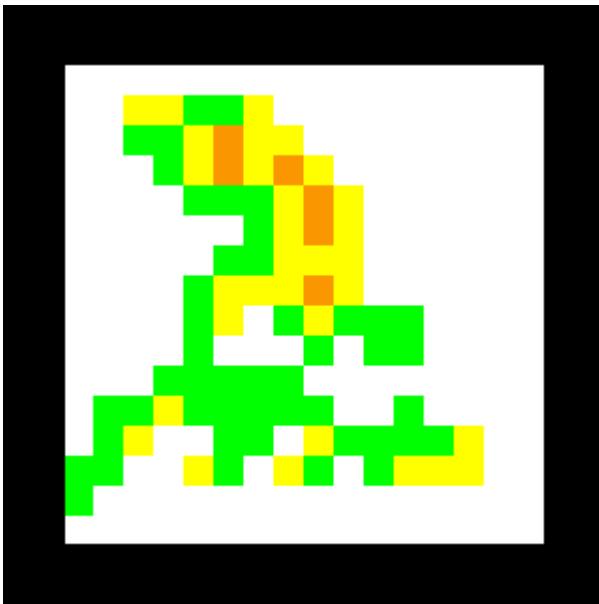
Observation



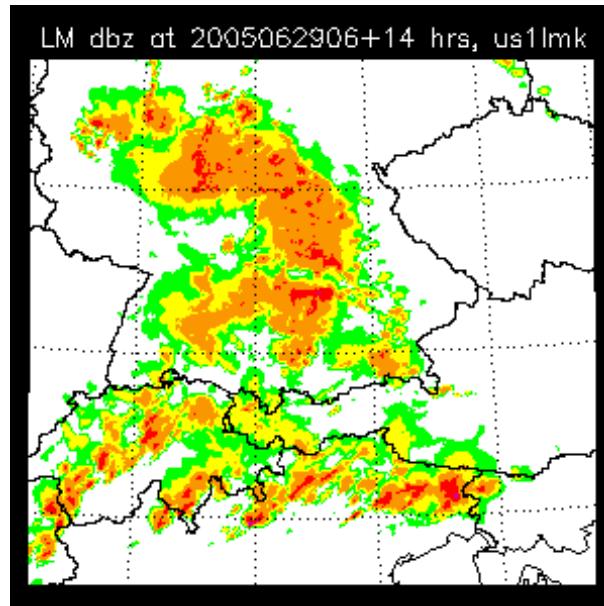
Coarse-grained observation

Pyramidal Matching: Example with real data

2. Coarse-grain both images by pixel averaging



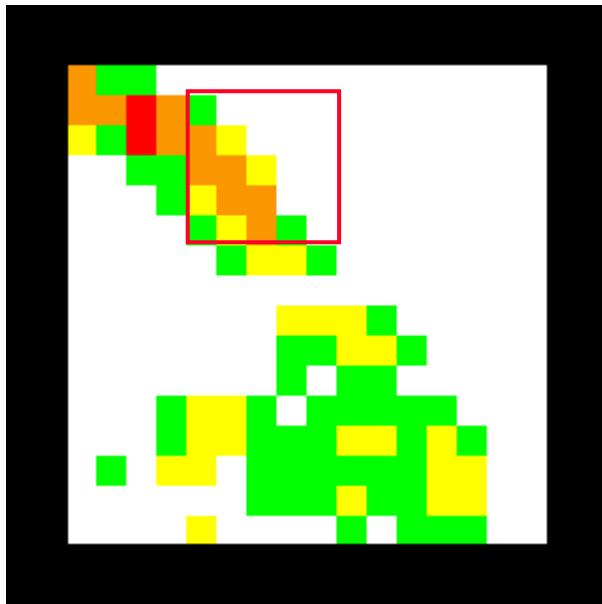
Coarse-grained forecast



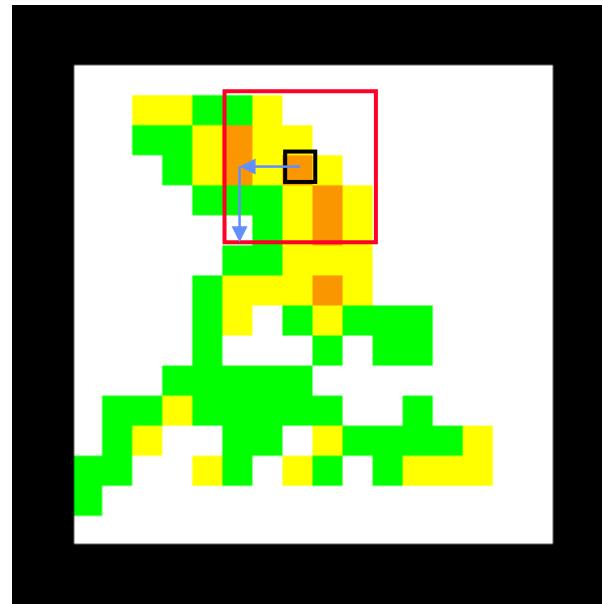
Forecast

Pyramidal Matching: Example with real data

3. Compute **displacement vector field** that minimizes the squared difference



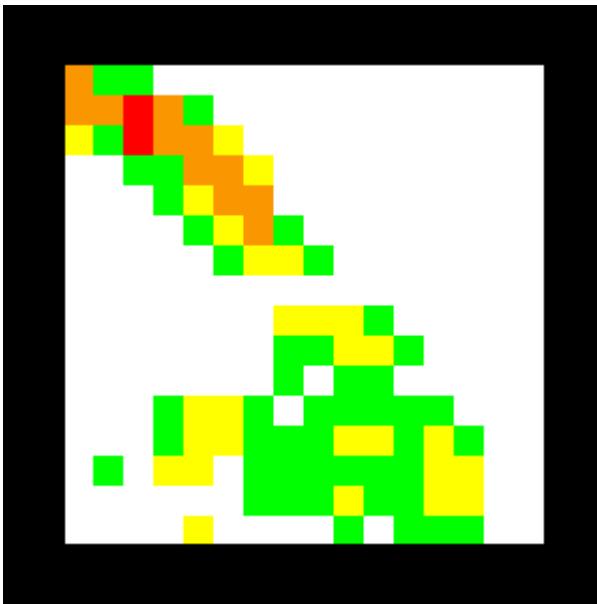
Observation



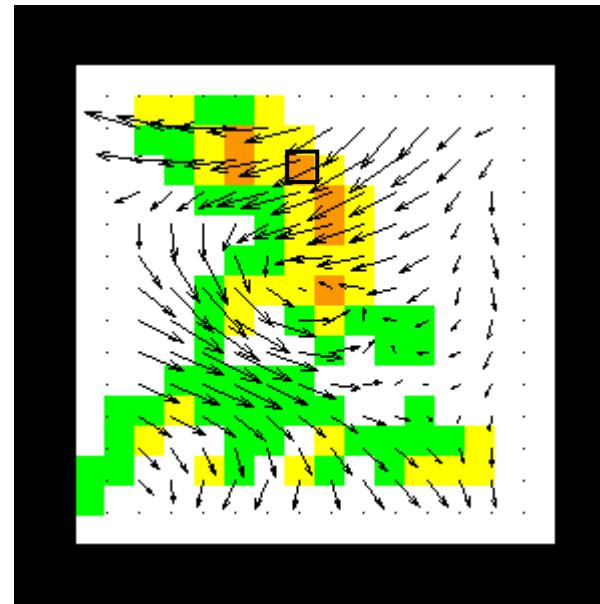
Forecast

Pyramidal Matching: Example with real data

3. Compute **displacement vector field** that minimizes the squared difference



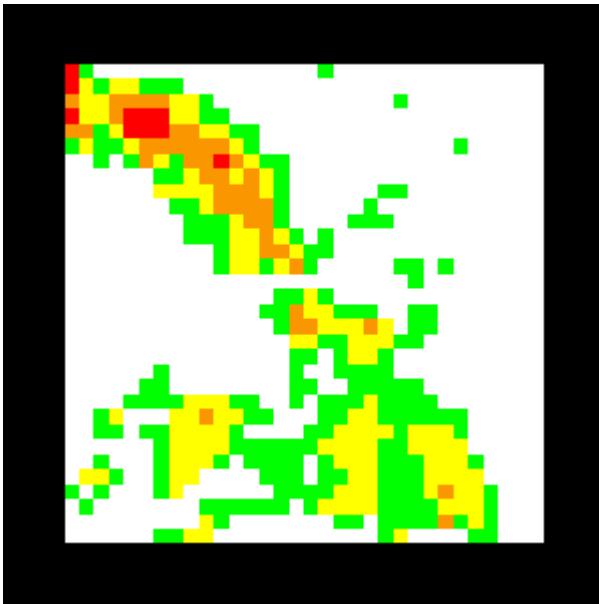
Observation



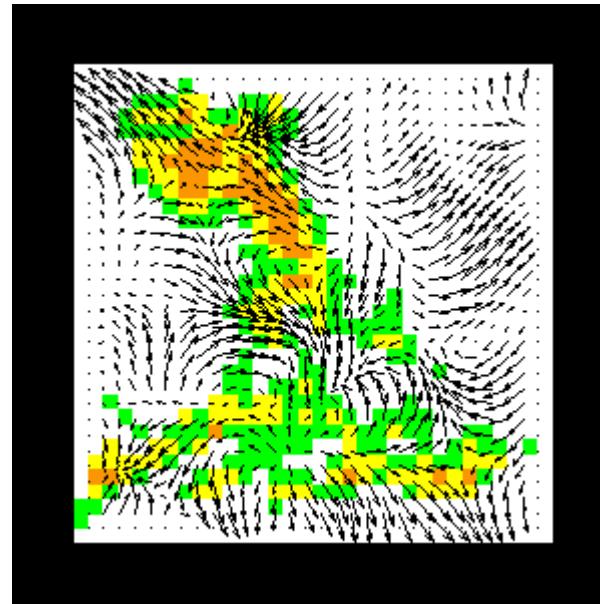
Forecast

Pyramidal Matching: Example with real data

4. Repeat step 3 at successively finer scales



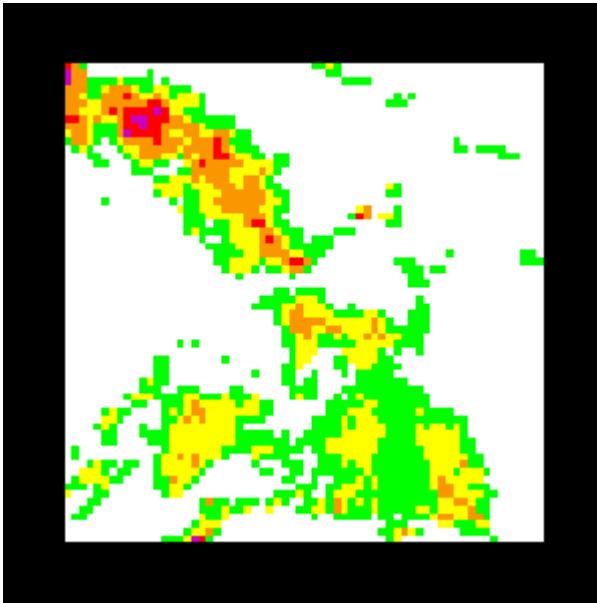
Observation



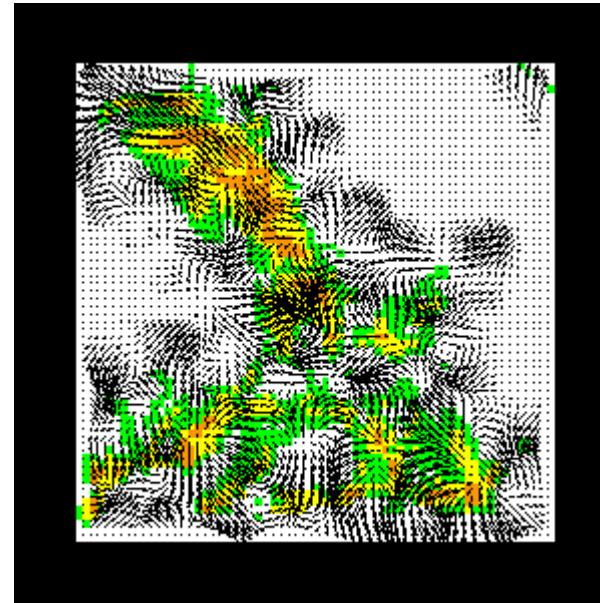
Forecast

Pyramidal Matching: Example with real data

4. Repeat step 3 at successively finer scales



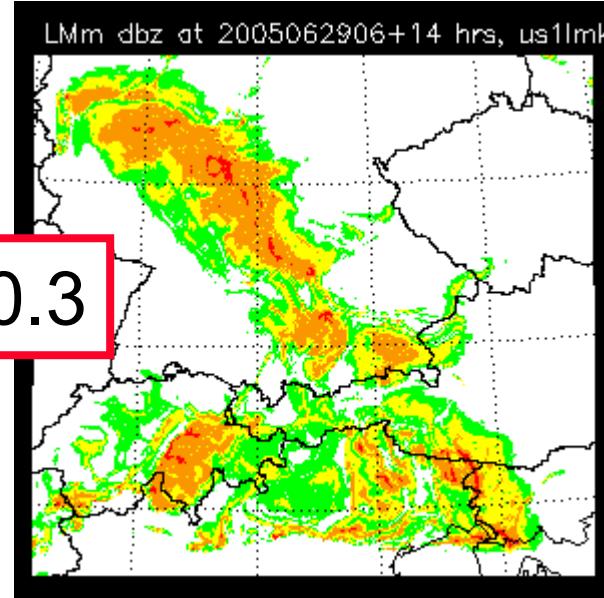
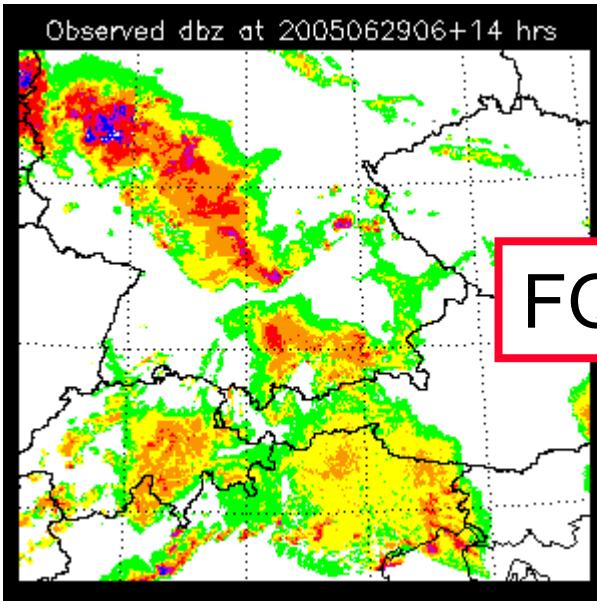
Observation



Forecast

Pyramidal Matching: Example with real data

5. Displacement vector for every pixel results from the **sum** over all scales



FQM = 0.3

Observation

Forecast

Forecast Quality Measure

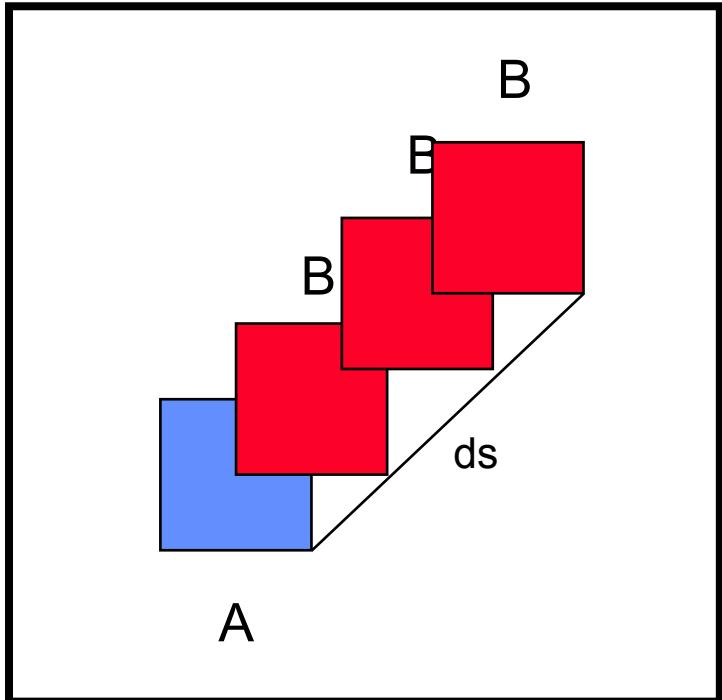
$$FQM = \frac{1}{A} \sum_A \max(c_1 \cdot DIS, c_2 \cdot LSE)$$

$$c_1 = DIS_{\max}^{-1}$$

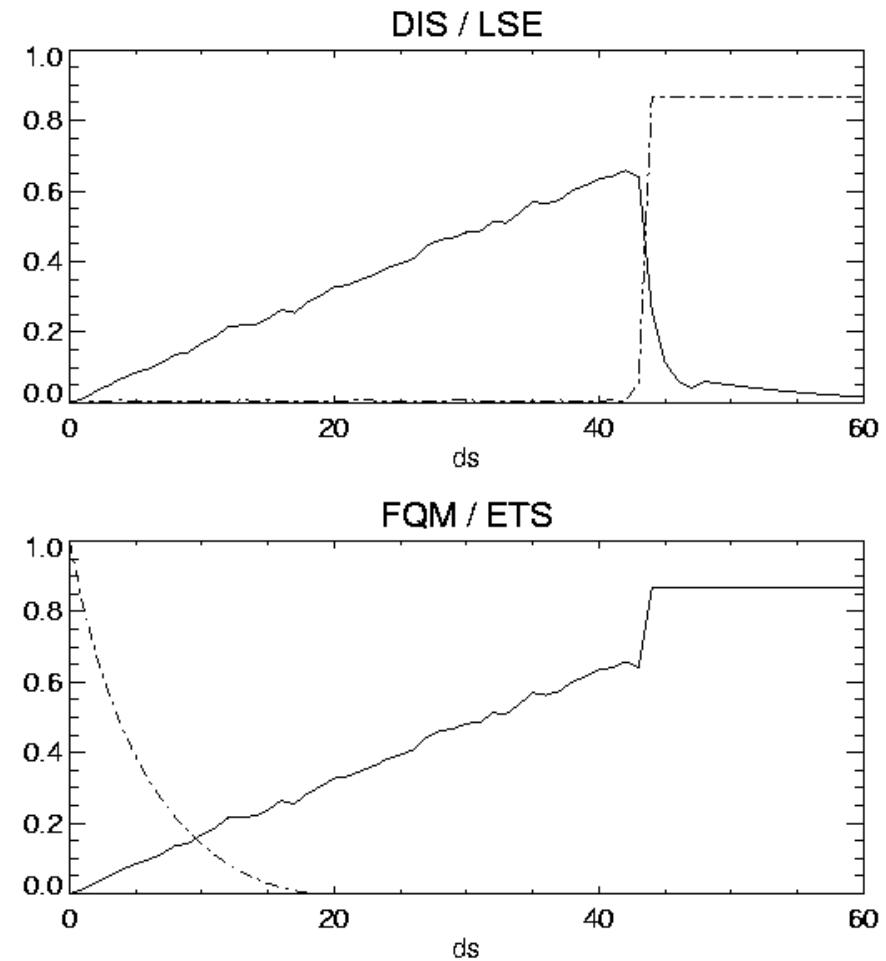
$$c_2 = (BT_{\max} - BT_{\min})^{-2}$$

If forecast and observed features can be matched, the magnitude of the displacement vector DIS characterises forecast quality, whereas when matching features cannot be found within the search distance, the local squared error LSE between both fields is used.

Simplified case



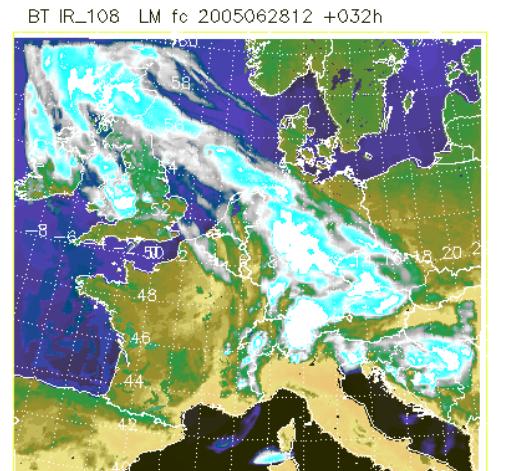
2 identical features
increasingly separated



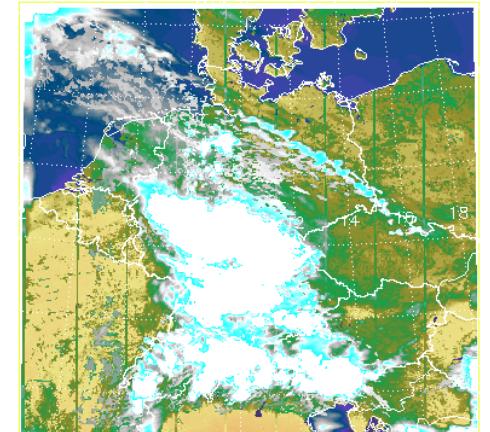
measures vs. separation distance

Applied in a Regional Ensemble Forecasting System

- COSMO-LEPS: based on ECMWF EPS providing initial and boundary conditions and Lokal-Modell (**LM $\Delta x=7\text{km}$**)
- LMSynSat: forward operator (RTTOV7) to compute **synthetic satellite imagery** in LM
- High resolution **LMK** experiments (**$\Delta x=2.8\text{km}$**) nested into representative members of COSMO-LEPS

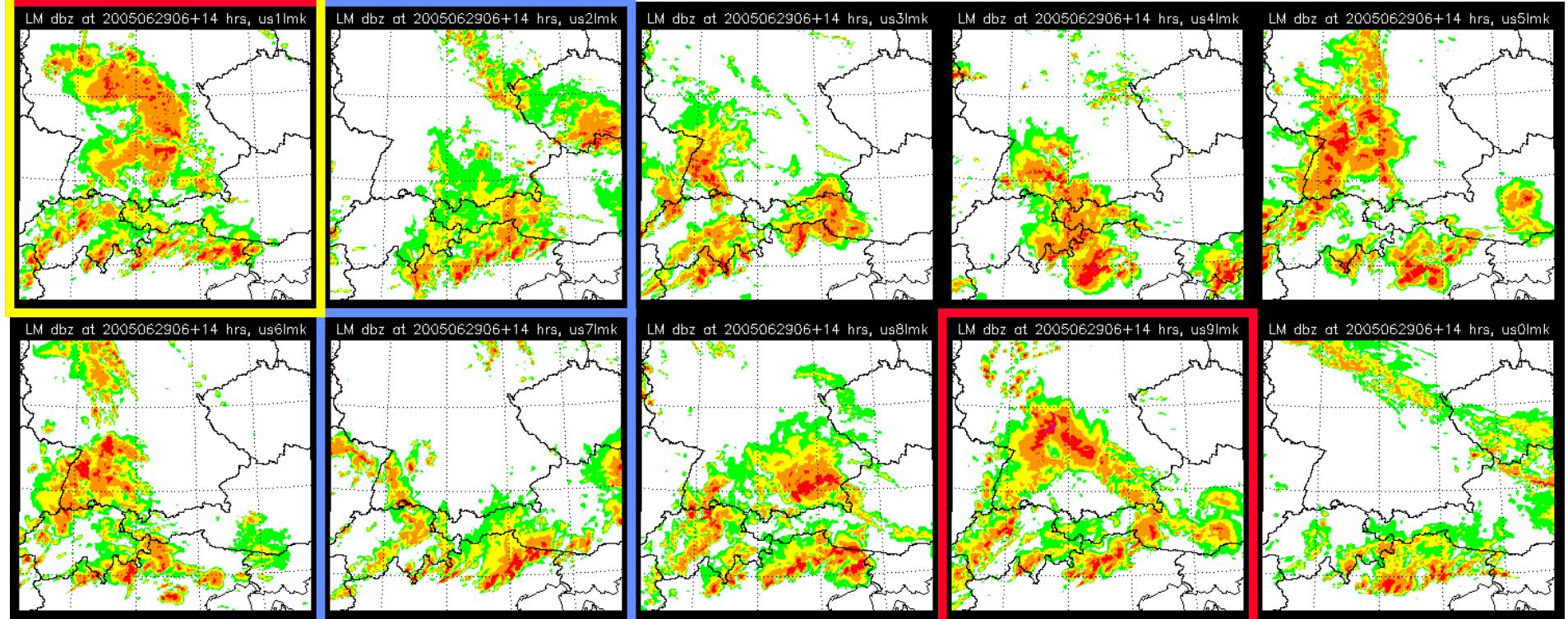
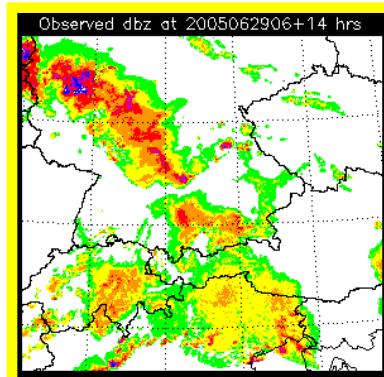


BT IR_108 LMK fc 2005062906 +014h

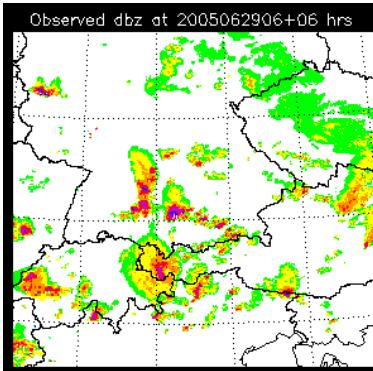


Applied in a Regional Ensemble Forecasting System on 29 June 2005

Radar 20:00 UTC

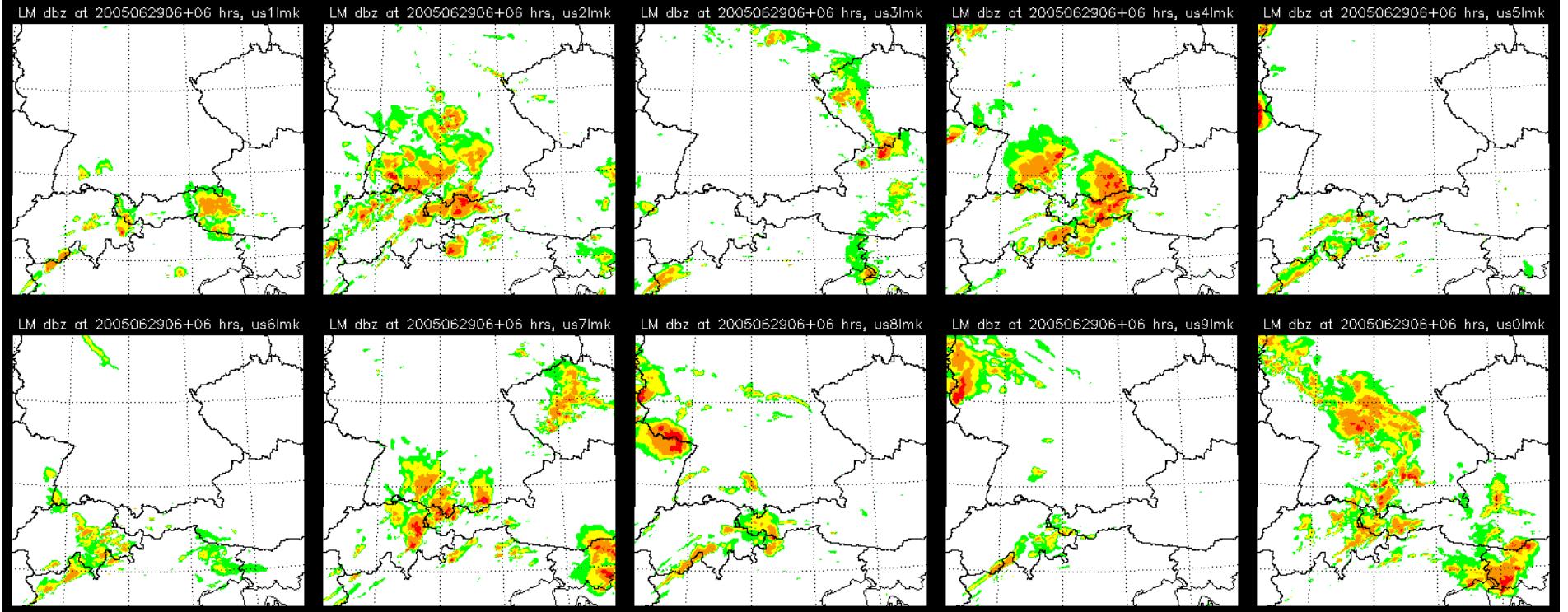


29 June 2005

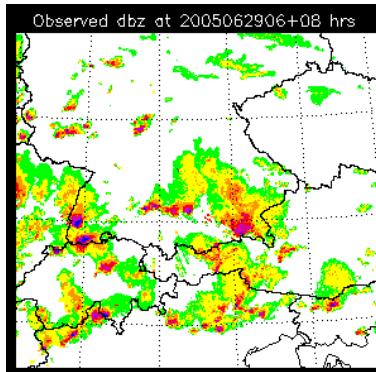


Radar 12:00 UTC

LMK: all 10 clusters

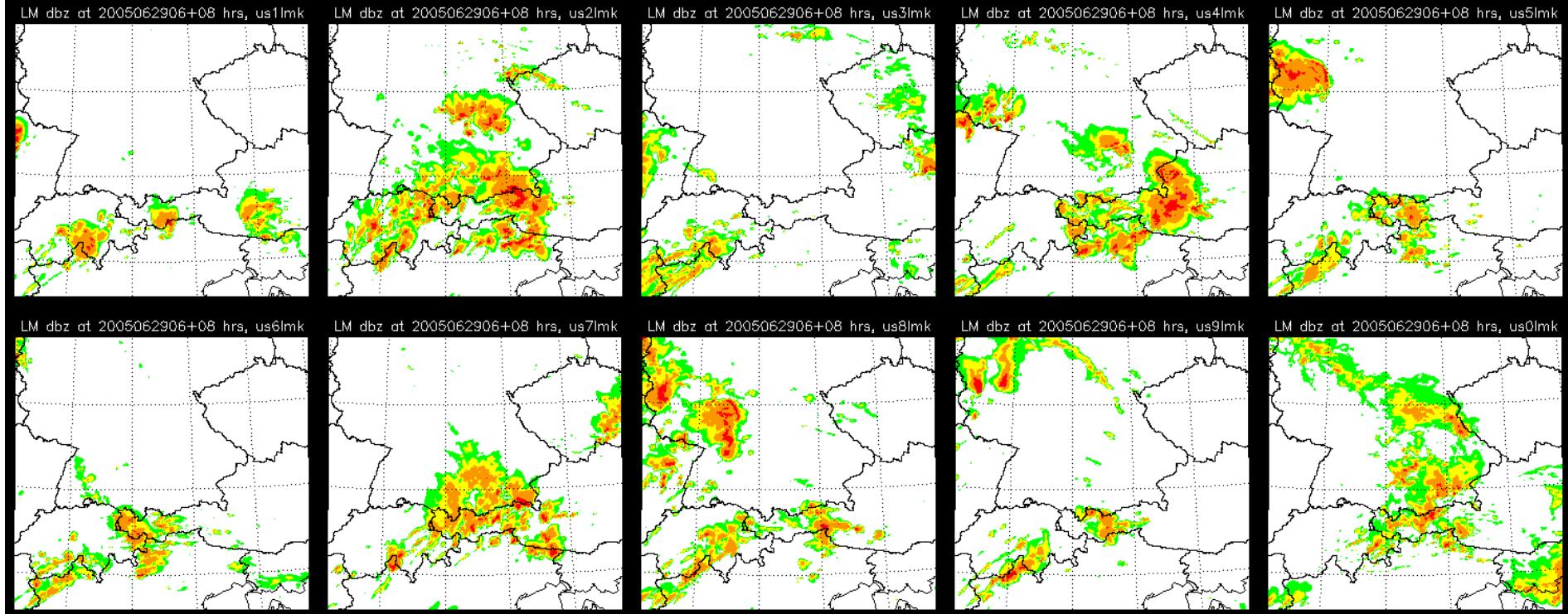


29 June 2005

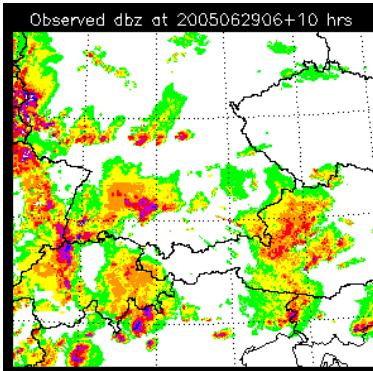


Radar 14:00 UTC

LMK: all 10 clusters

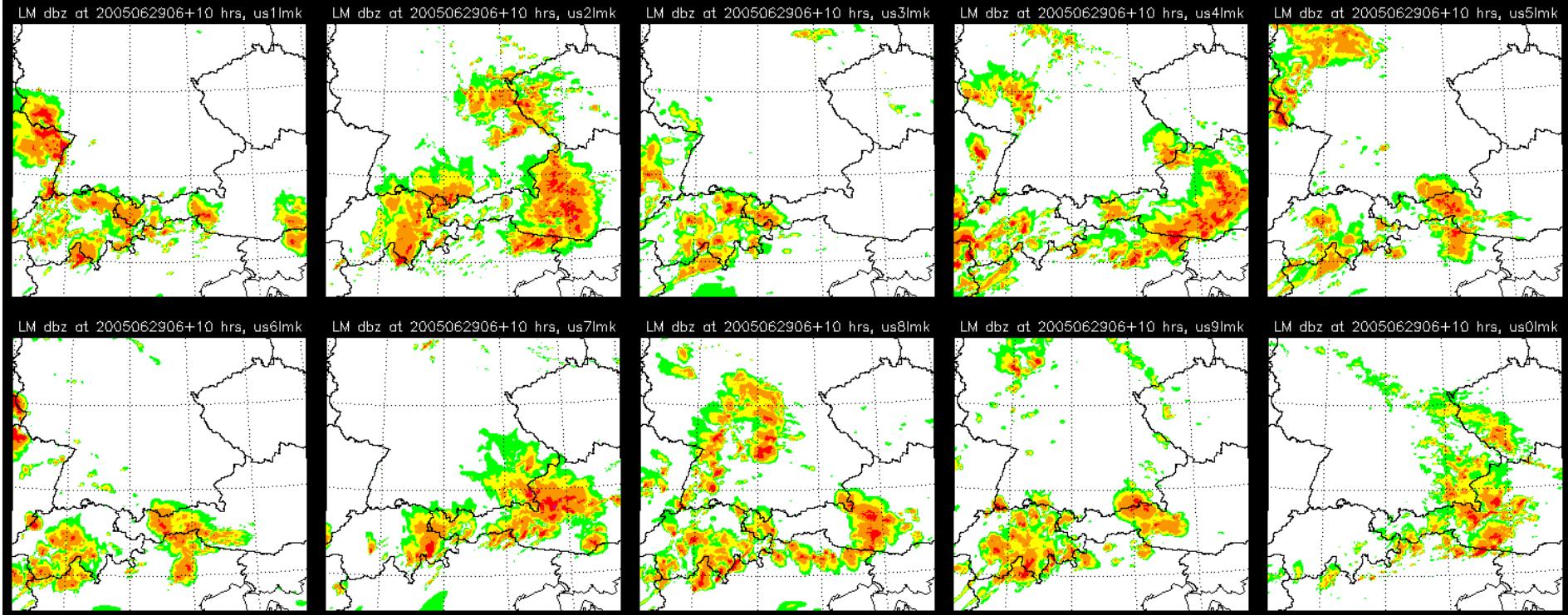


29 June 2005

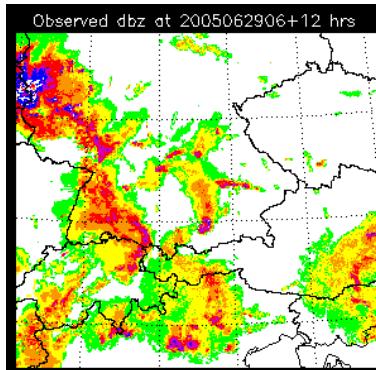


Radar 16:00 UTC

LMK: all 10 clusters

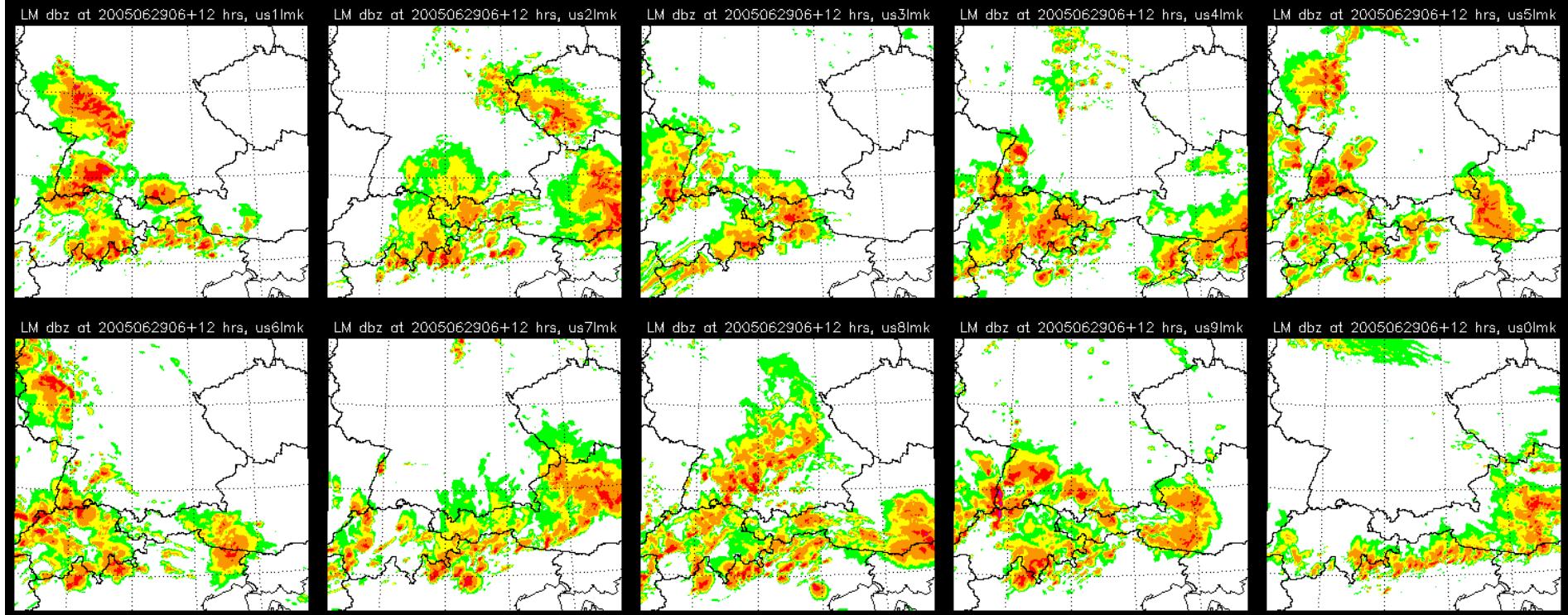


29 June 2005

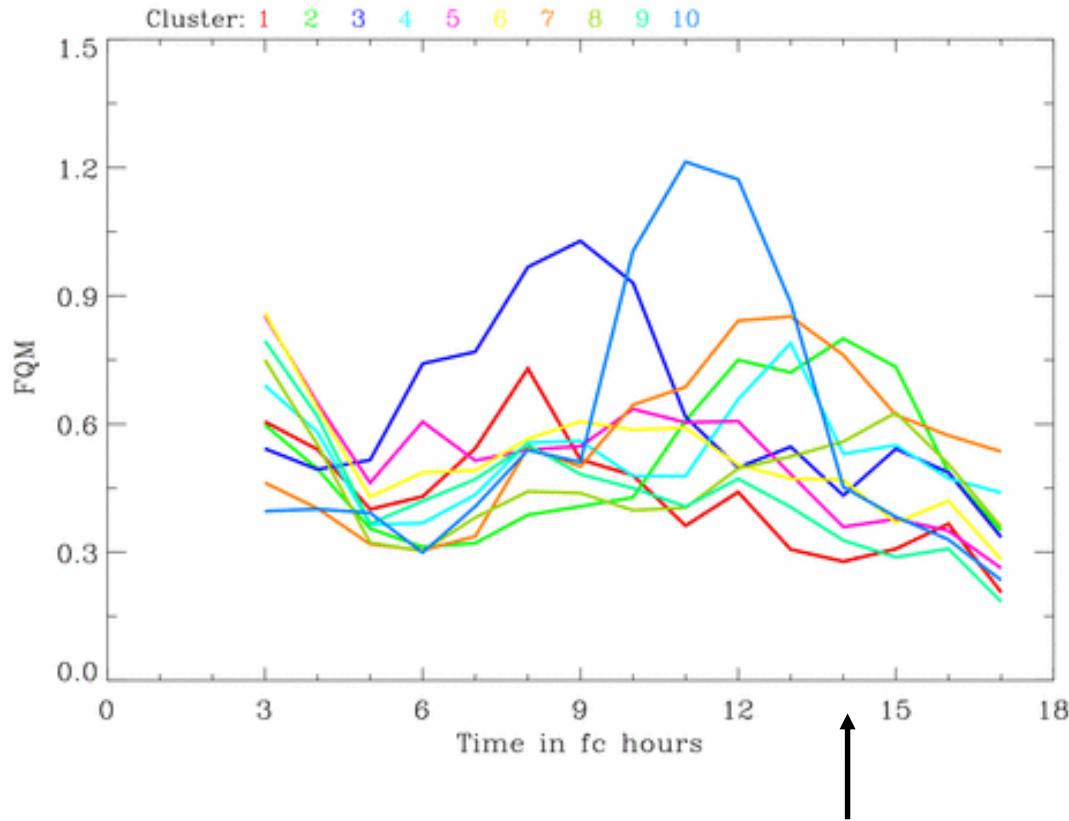


Radar 18:00 UTC

LMK: all 10 clusters

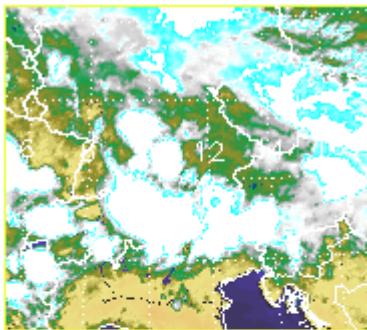


Forecast Quality of LMK based on Radar data



29 June 2005

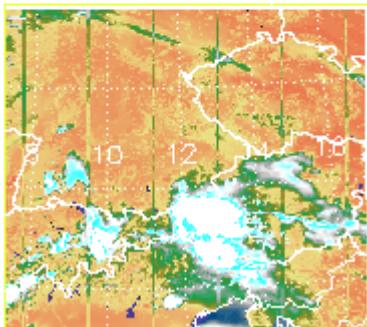
BT IR_10.8 METS 2005062906 12 UTC



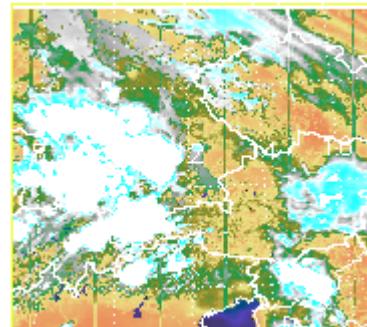
Meteosat 8 IR10.8 12:00 UTC

LMK: all 10 clusters

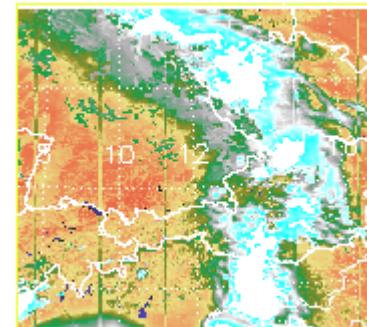
BT IR LMK fc 2005062906 +0600h



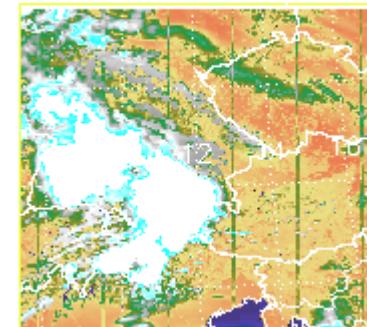
BT IR LMK fc 2005062906 +0600h



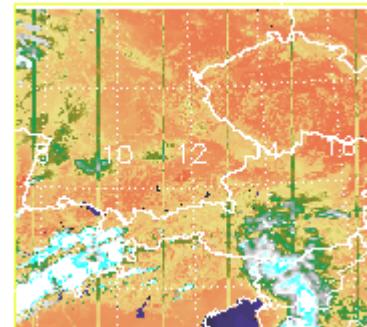
BT IR LMK fc 2005062906 +0600h



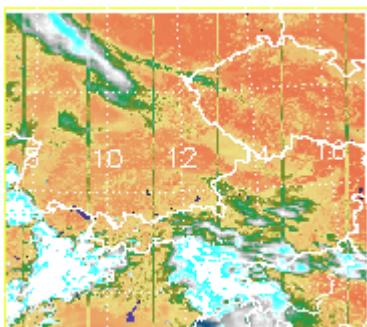
BT IR LMK fc 2005062906 +0600h



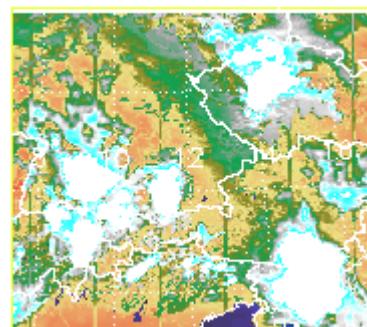
BT IR LMK fc 2005062906 +0600h



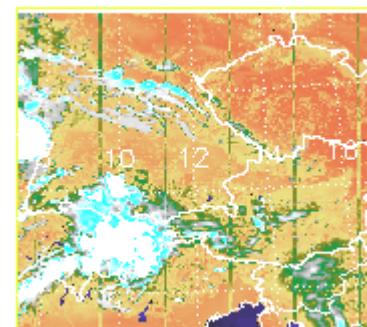
BT IR LMK fc 2005062906 +0600h



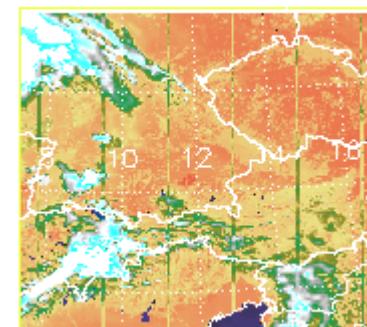
BT IR LMK fc 2005062906 +0600h



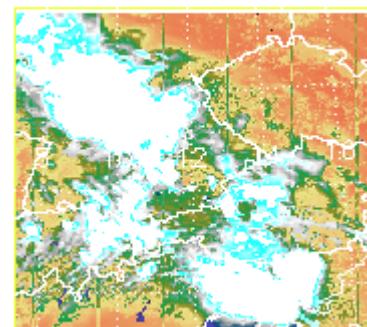
BT IR LMK fc 2005062906 +0600h



BT IR LMK fc 2005062906 +0600h

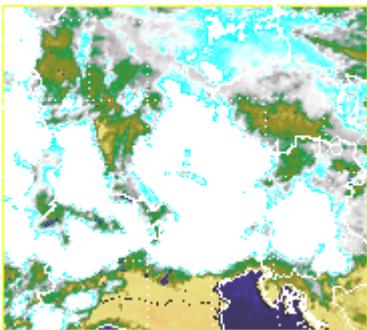


BT IR LMK fc 2005062906 +0600h



29 June 2005

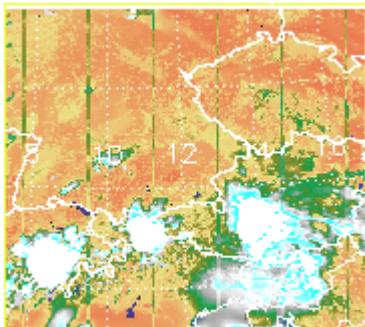
BT IR_10.8 METS 2005062906 14 UTC



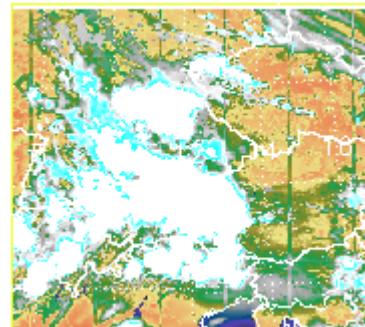
Meteosat 8 IR10.8 14:00 UTC

LMK: all 10 clusters

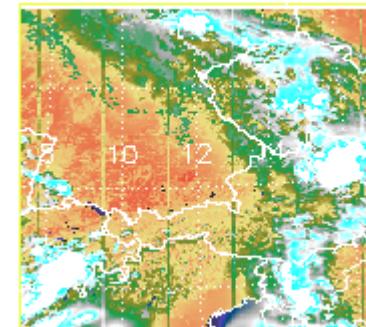
BT IR LMK fc 2005062906 +0600h



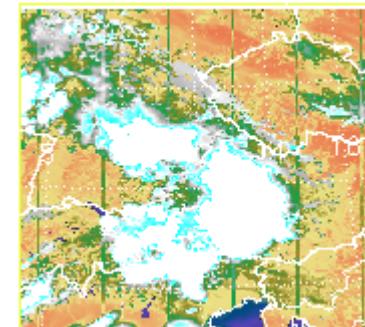
BT IR LMK fc 2005062906 +0600h



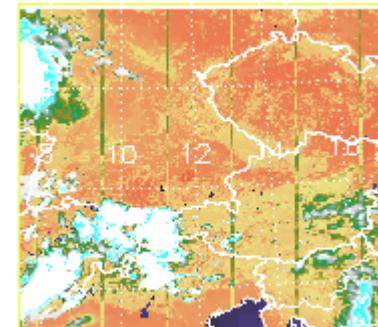
BT IR LMK fc 2005062906 +0600h



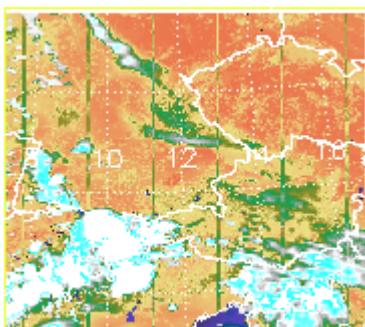
BT IR LMK fc 2005062906 +0600h



BT IR LMK fc 2005062906 +0600h



BT IR LMK fc 2005062906 +0600h



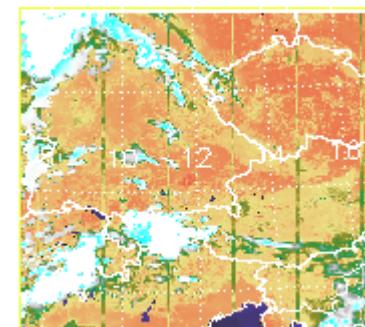
BT IR LMK fc 2005062906 +0600h



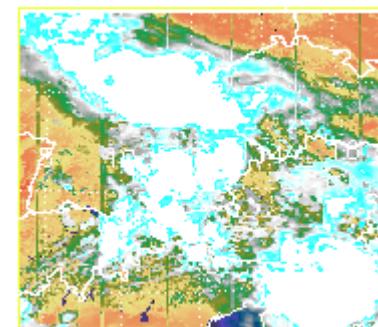
BT IR LMK fc 2005062906 +0600h



BT IR LMK fc 2005062906 +0600h

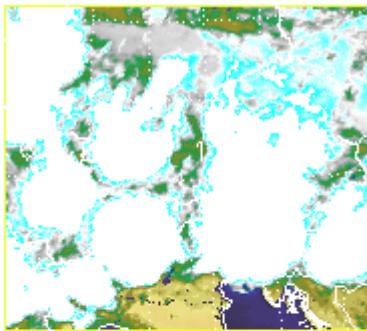


BT IR LMK fc 2005062906 +0600h



29 June 2005

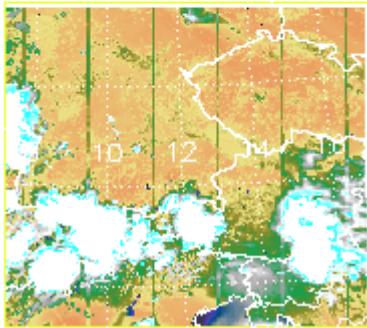
BT IR_10.8 METS 2005062906 16 UTC



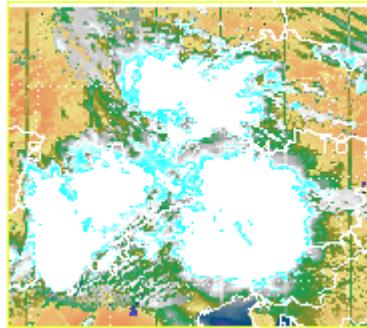
Meteosat 8 IR10.8 16:00 UTC

LMK: all 10 clusters

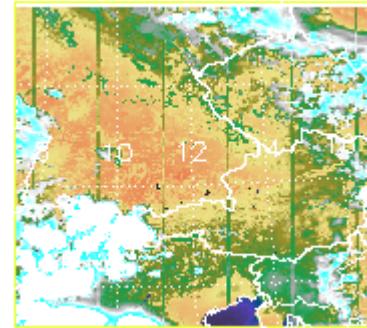
BT IR LMK fc 2005062906 +1000h



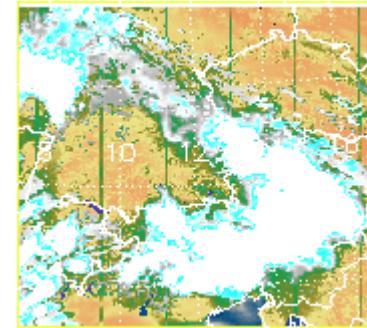
BT IR LMK fc 2005062906 +1000h



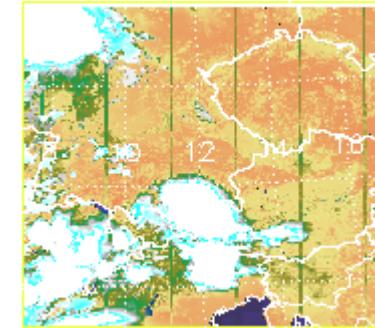
BT IR LMK fc 2005062906 +1000h



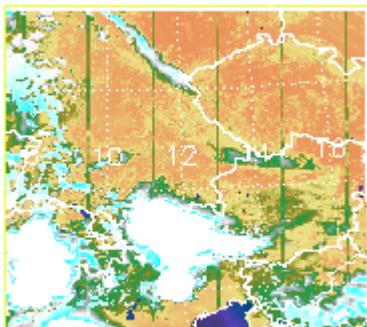
BT IR LMK fc 2005062906 +1000h



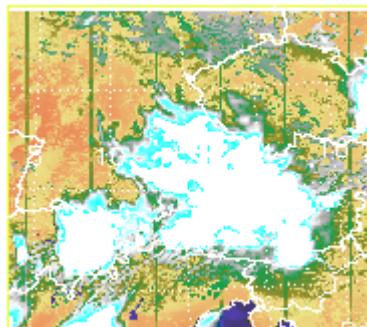
BT IR LMK fc 2005062906 +1000h



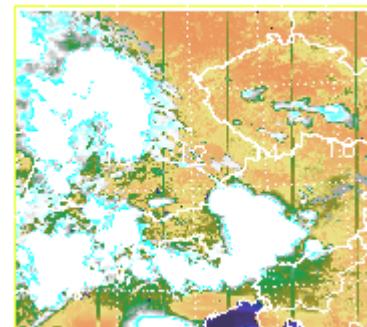
BT IR LMK fc 2005062906 +1000h



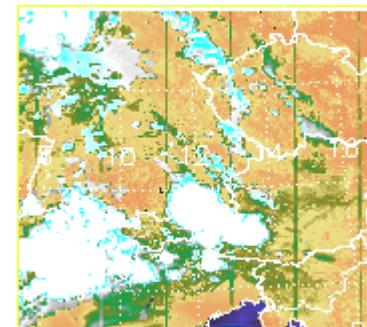
BT IR LMK fc 2005062906 +1000h



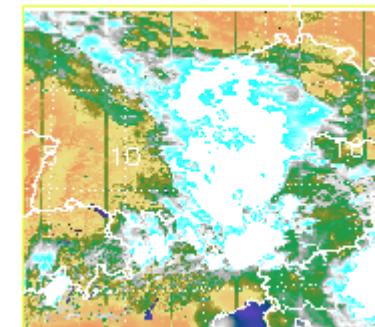
BT IR LMK fc 2005062906 +1000h



BT IR LMK fc 2005062906 +1000h

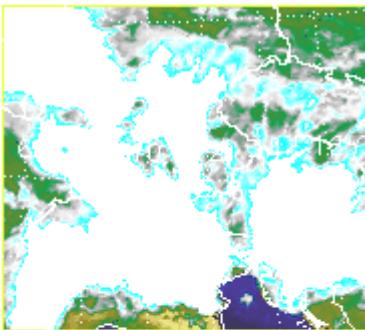


BT IR LMK fc 2005062906 +1000h



29 June 2005

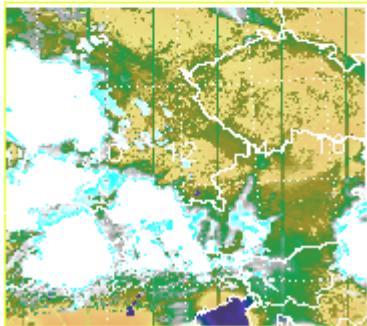
BT IR_10.8 MET8 2005062906 18 UTC



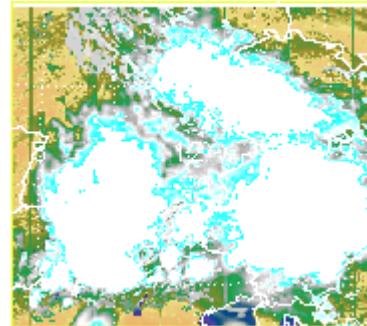
Meteosat 8 IR10.8 18:00 UTC

LMK: all 10 clusters

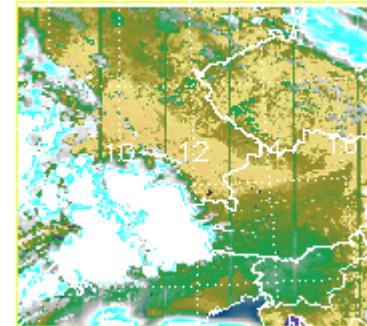
BT IR LMK fc 2005062906 +1200h



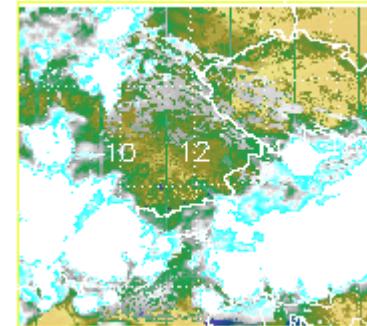
BT IR LMK fc 2005062906 +1200h



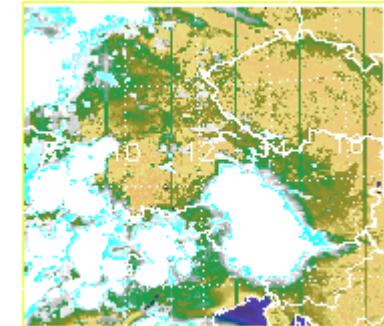
BT IR LMK fc 2005062906 +1200h



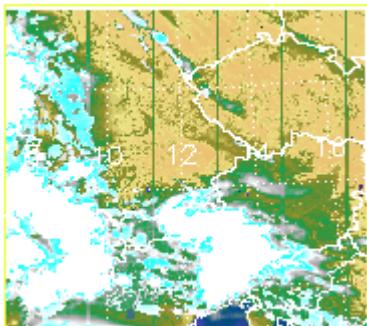
BT IR LMK fc 2005062906 +1200h



BT IR LMK fc 2005062906 +1200h



BT IR LMK fc 2005062906 +1200h



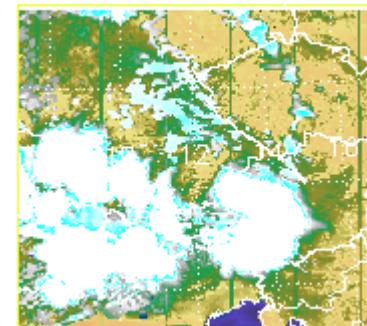
BT IR LMK fc 2005062906 +1200h



BT IR LMK fc 2005062906 +1200h



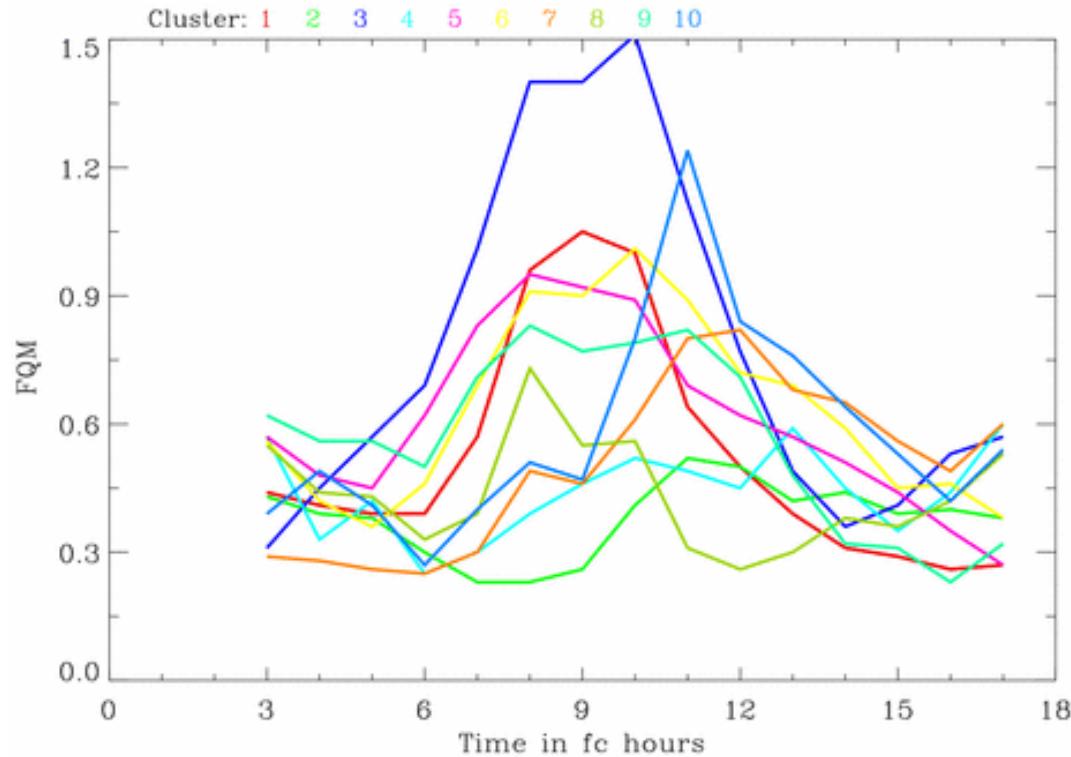
BT IR LMK fc 2005062906 +1200h



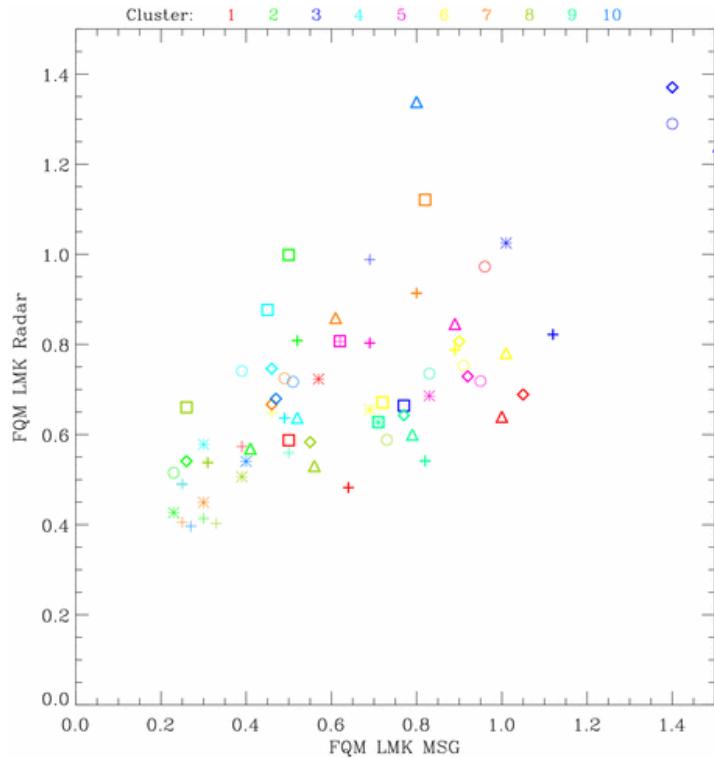
BT IR LMK fc 2005062906 +1200h



Forecast Quality of LMK based on Satellite data



Forecast Quality of LMK based on Satellite vs Radar data



Correlation FQM(MSG vs Radar) = 0.73

Summary, conclusions and outlook

- The novel Forecast Quality Measure allows an objective evaluation based on image comparison.

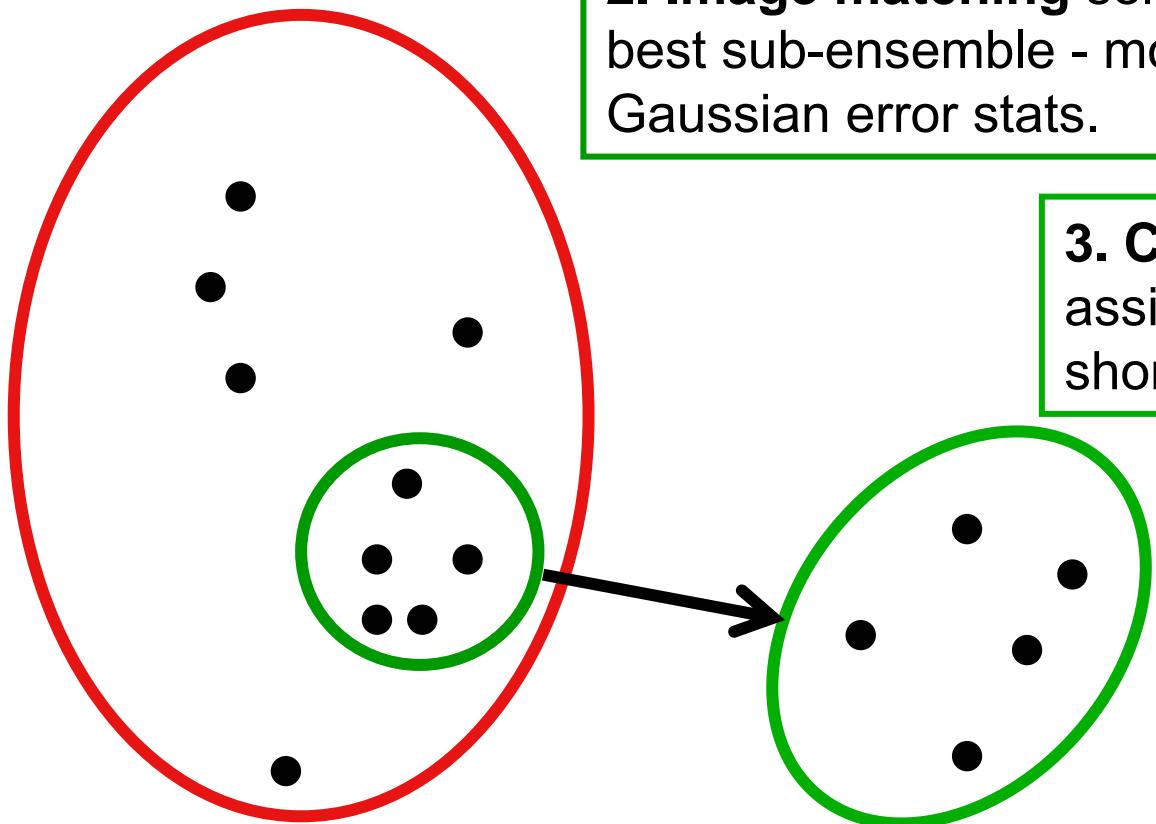
Keil, C. and G. C. Craig, 2006: A Displacement-based Error Measure applied in a Regional Ensemble Forecasting System, *Mon. Wea. Rev.*, submitted.
- Comparison of Regional Ensemble Forecasts with Radar and Satellite data provides consistent results.
- Systematic evaluation planned during DOP in 2007
- Radar rainfall assimilation experiments in selected members which are favourable for convection (in collaboration with MeteoSwiss)

Goal: Image matching as pre-conditioner for DA

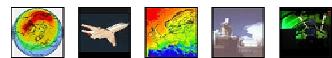
1. COSMO-LEPS ensemble forecast -
highly non-Gaussian error stats.

2. Image matching selects
best sub-ensemble - more
Gaussian error stats.

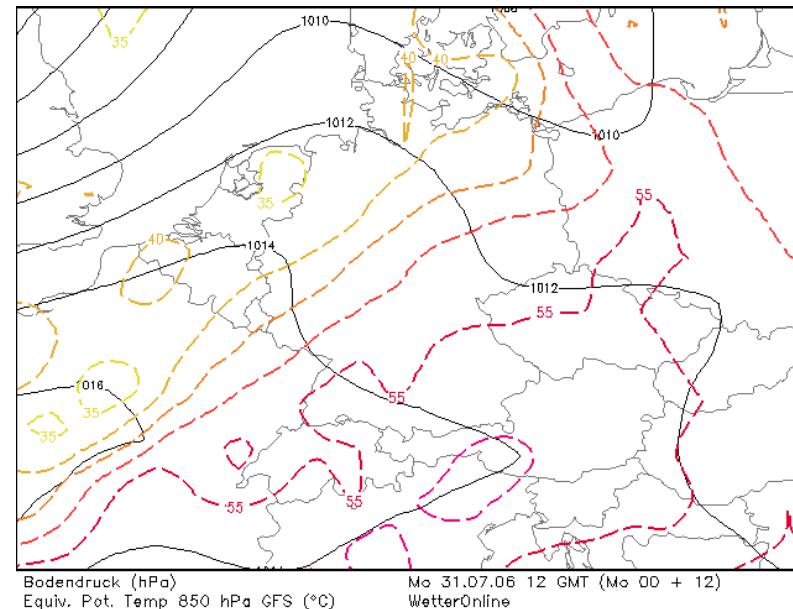
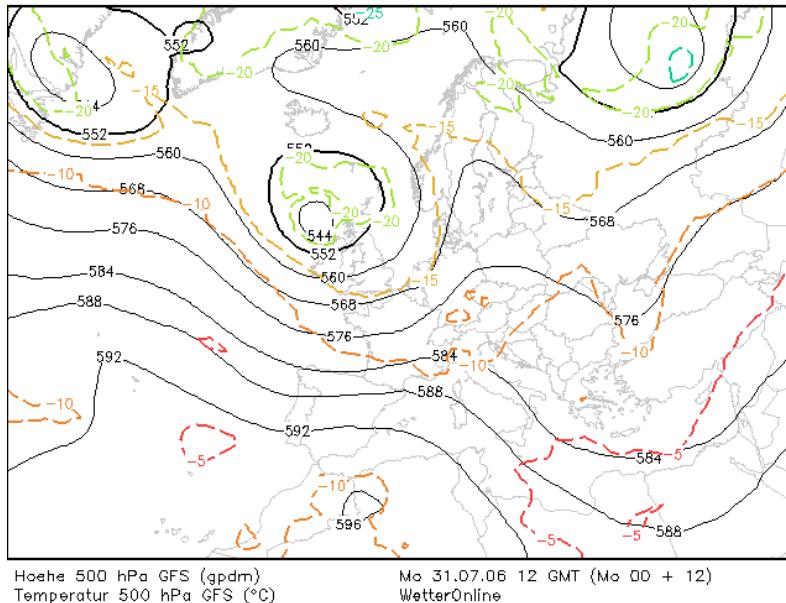
3. Conventional DA
assimilates most recent data for
short-range forecast



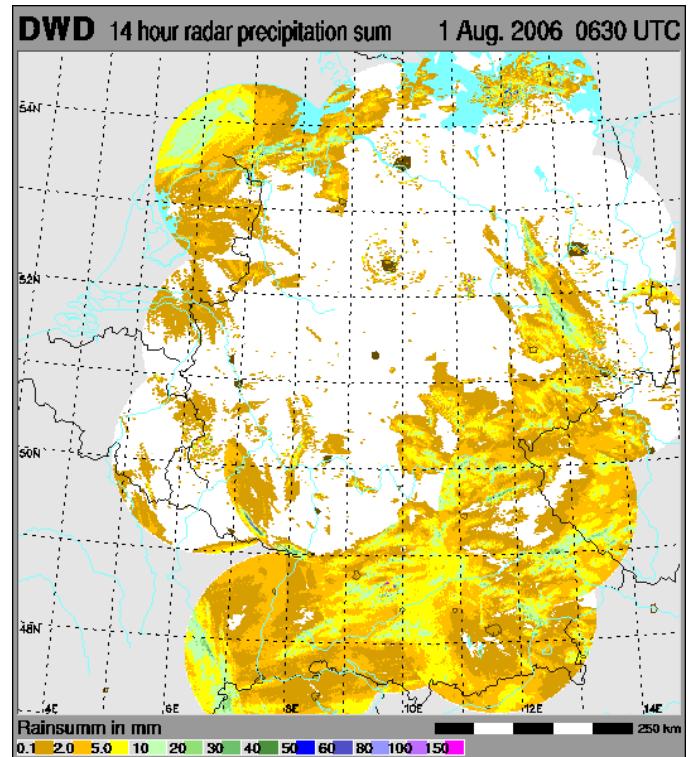
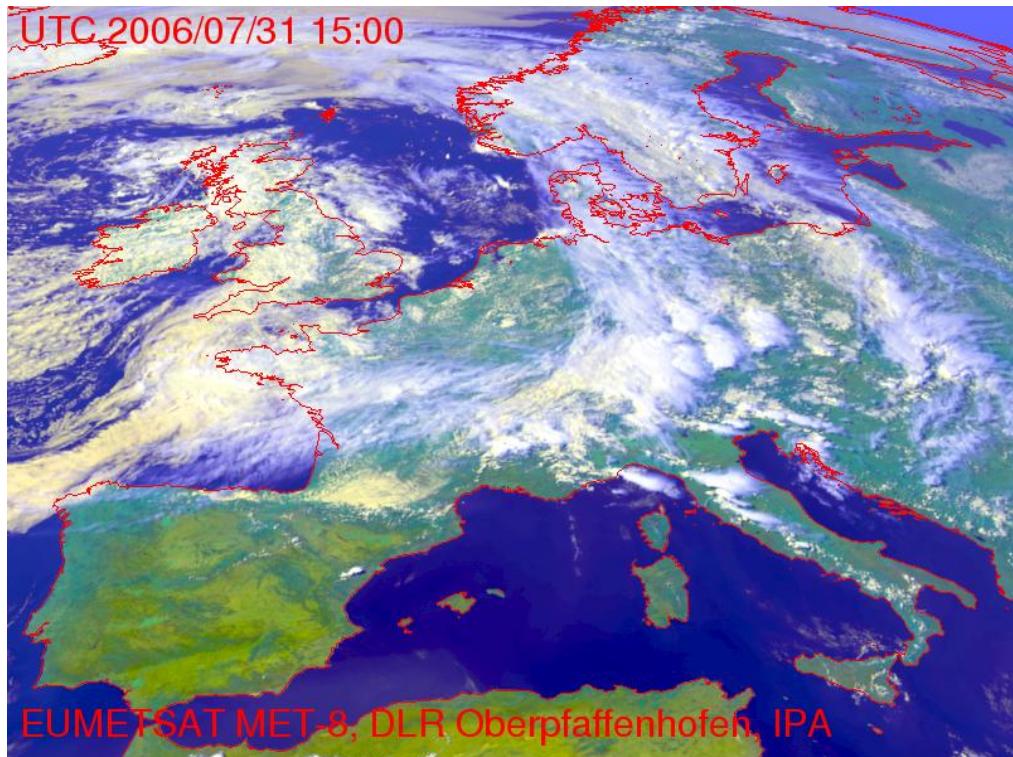
DAQUA Ensemble Experiments JJA 2006 (tbd)



Type I: 20060731

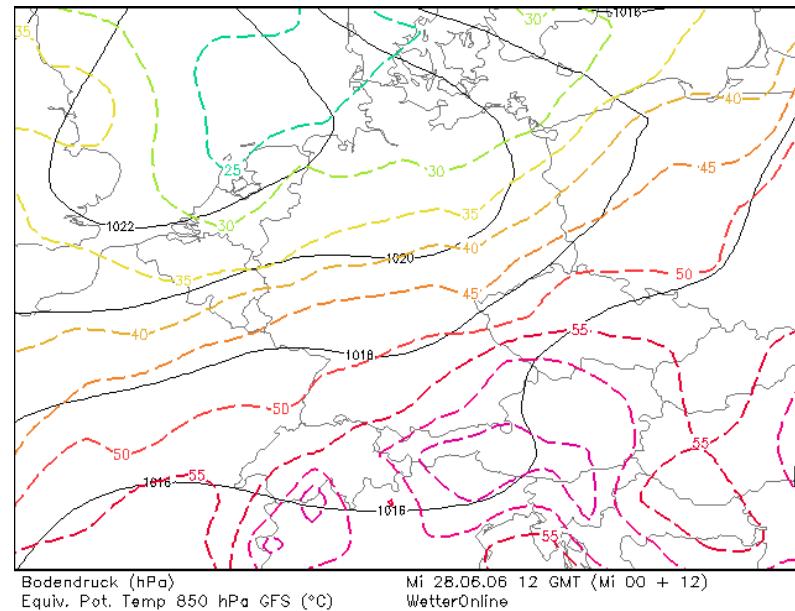
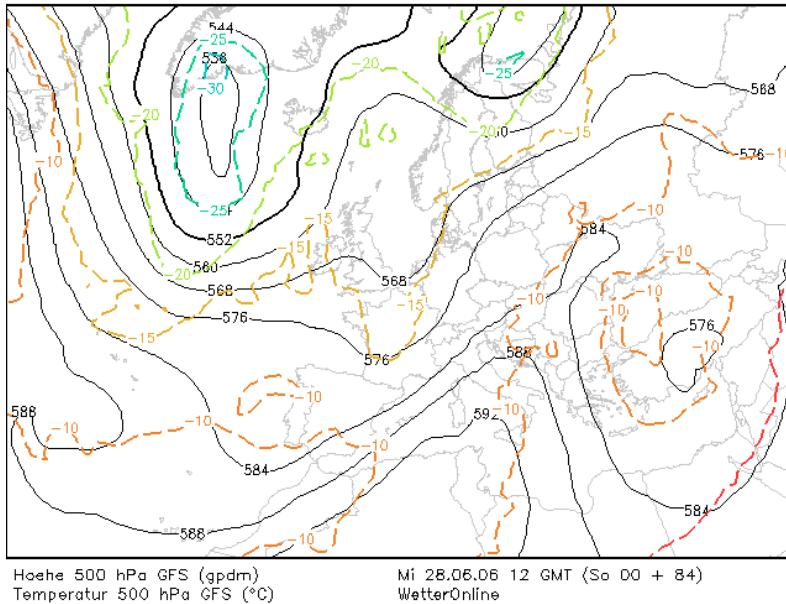


Type I: 20060731

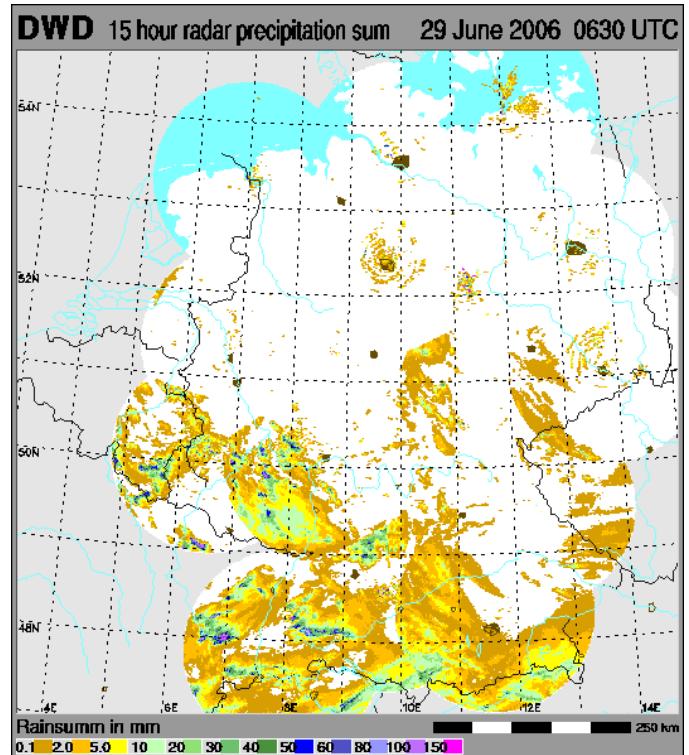
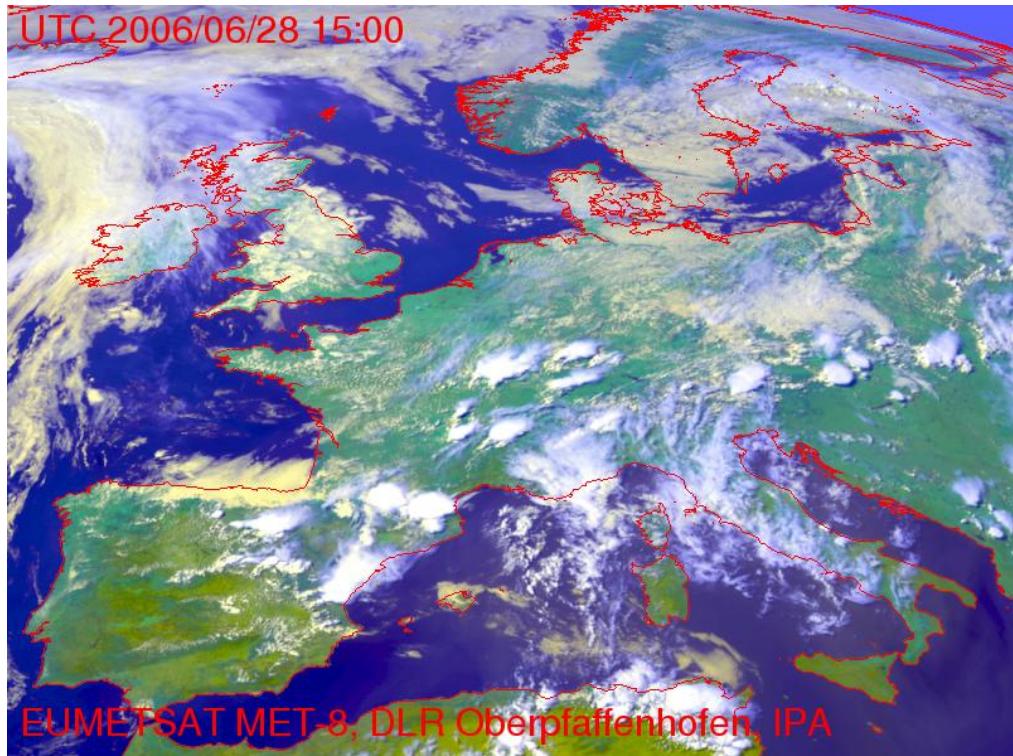


24h precip: Feldberg	20 mm
Freiburg	2 mm
Freudenstadt	13 mm
Klippenbeck	27 mm

Type II: 20060628

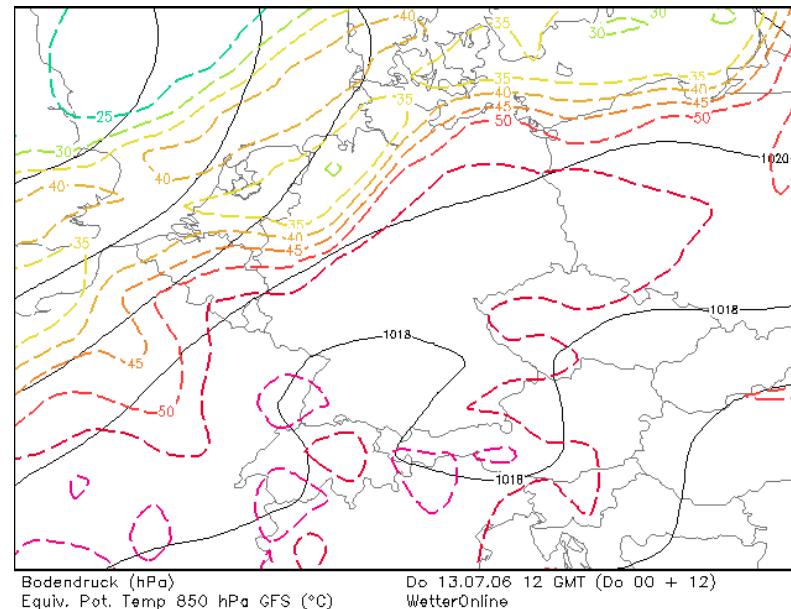
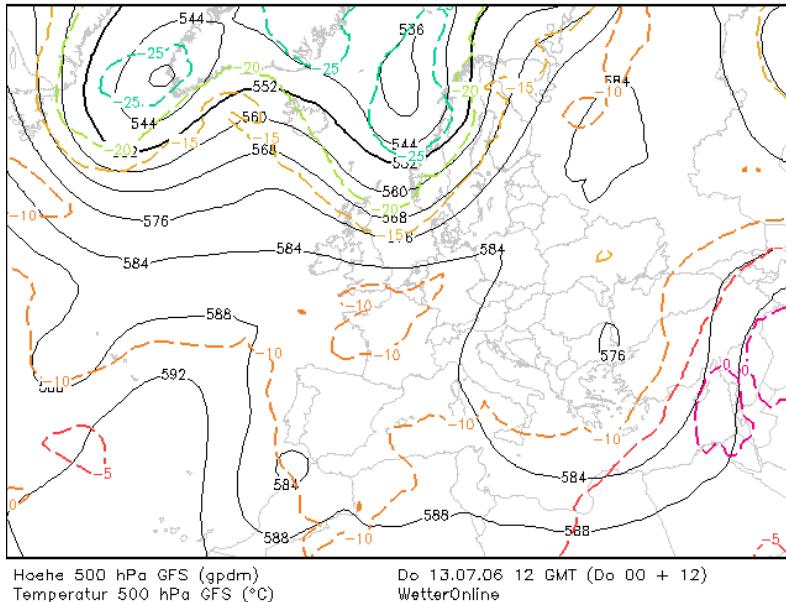


Type II: 20060628

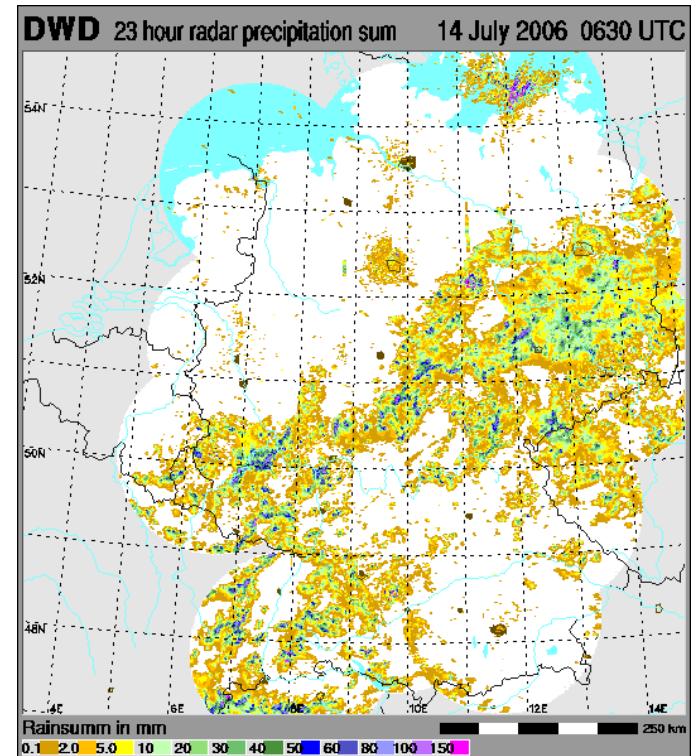
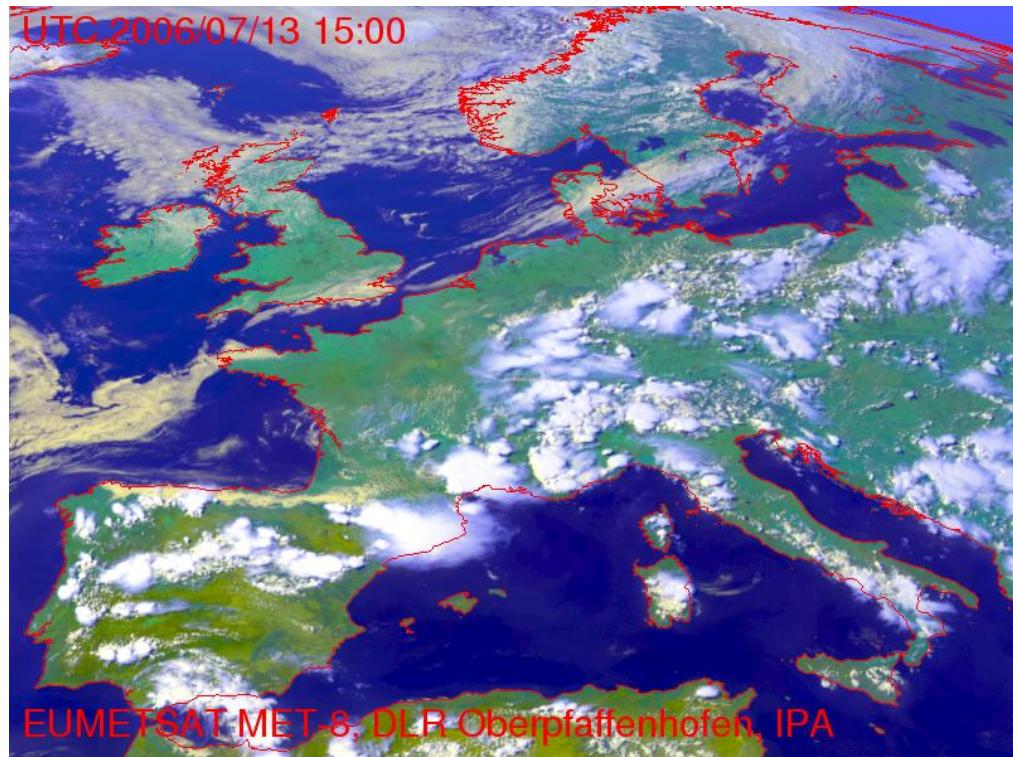


24h precip: Feldberg	4 mm
Freiburg	--
Freudenstadt	13 mm
Klippenbeck	22 mm

Type III: 20060713

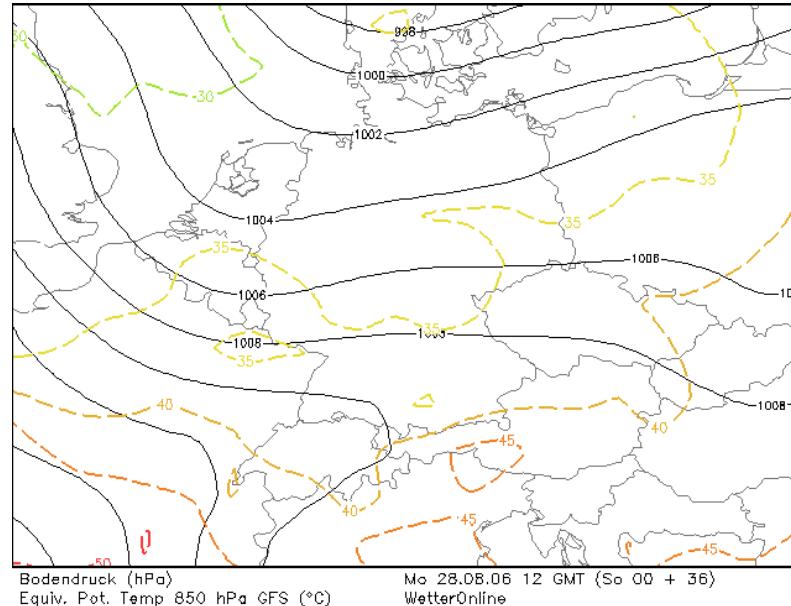
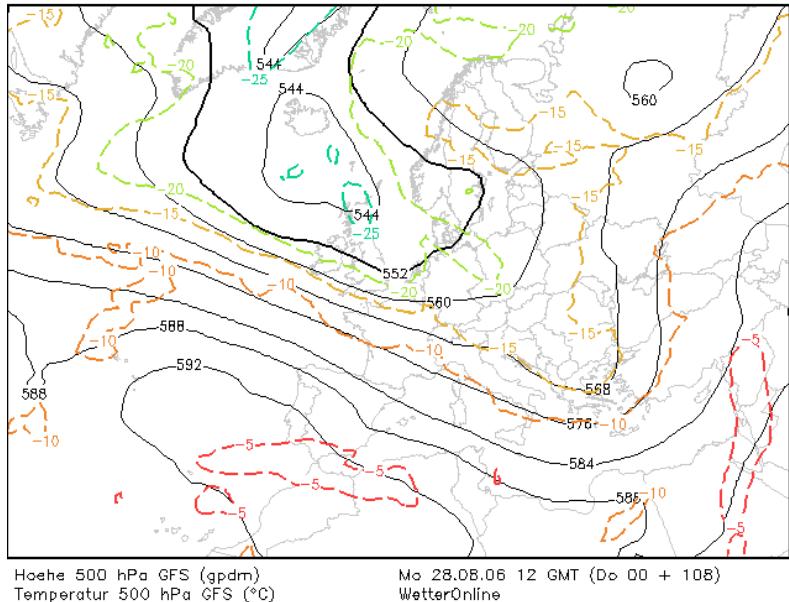


Type III: 20060713

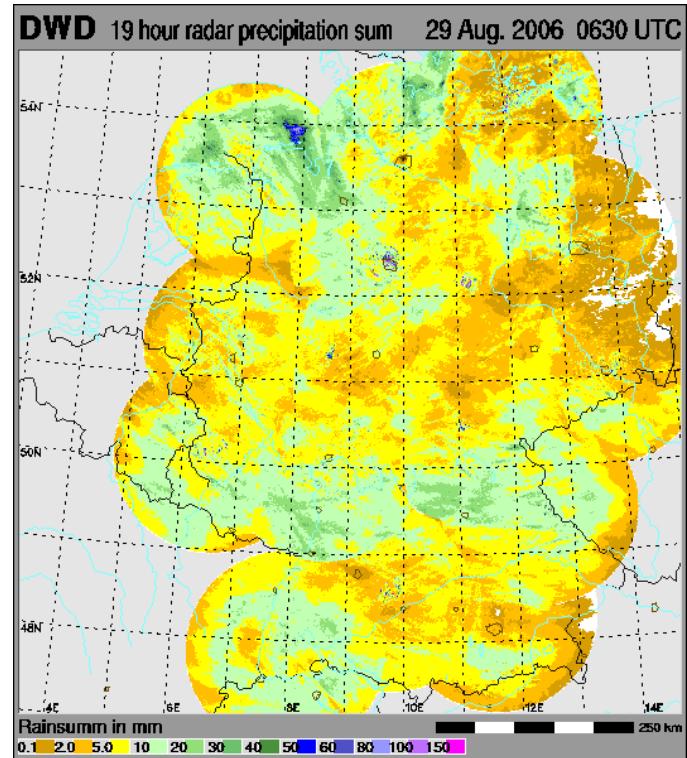
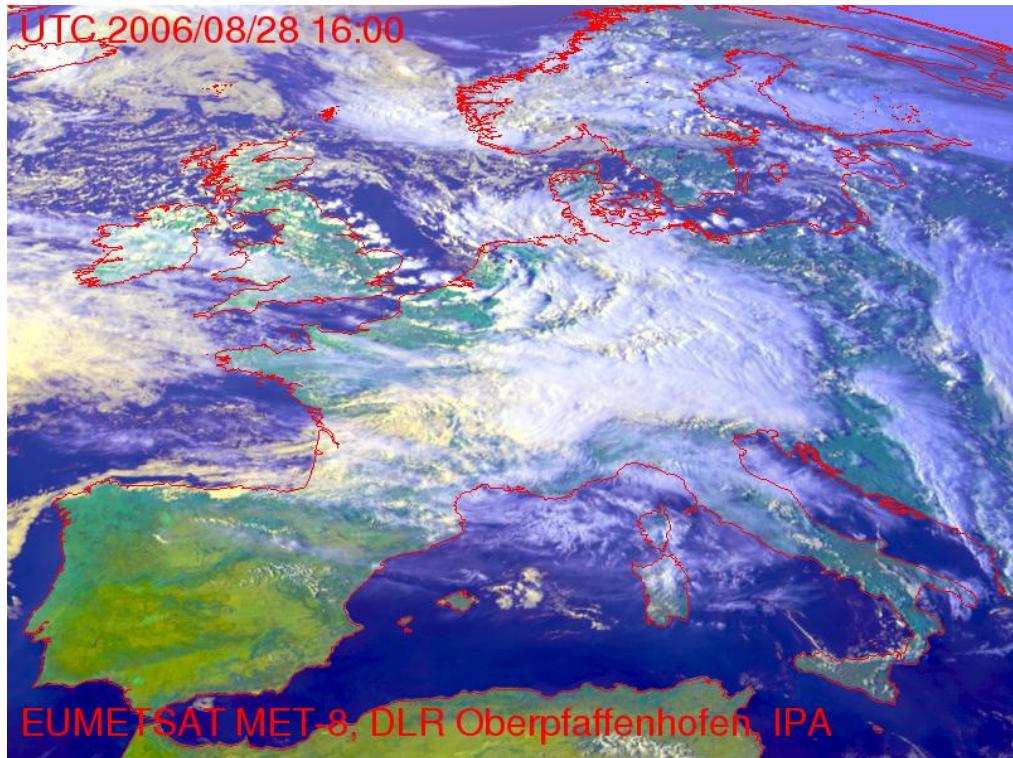


24h precip: Feldberg	< 5 mm
Freiburg	--
Freudenstadt	--
Klippenbeck	< 5 mm

Type IIb: 20060828



Type IIb: 20060828

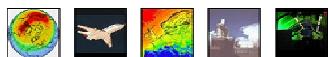


24h precip: Feldberg	38 mm
Freiburg	14 mm
Freudenstadt	28 mm
Klippenbeck	13 mm

Generation of synthetic satellite images in LM: LMSynSat

- RTTOV-7 radiative transfer model (Saunders et al, 1999)
- Input: 3D fields: T,qv,qc,qi,qs,clc,ozone
surface fields: T_g, T_2m, qv_2m, fr_land
- Output: cloudy/clear-sky brightness temperatures for
Meteosat7 (IR and WV channels) and
Meteosat8 (eight channels)

(Keil et al, 2006)



Met-8 IR & Radar composite sequences

